

# Vibration Compensator EMC Series (Electric Moment Compensator)





Horizontal Type



- Effectively decreases vibrations that are difficult to manage through manual methods.
- Cost-effective and quick solution for reducing ship propulsion







### **Horizontal Type**

Horizontal compensation device is installed on the deck house or engine top to reduce vibro-motive force caused by H or X-moment of the main engine guideforce, decreasing vibrations in the ship girder, D/H and main engine body.

### **Vertical Type**

Vertical compensation device is installed in the steering gear room or on the mooring desk and used to effective reduce the vertical hull girder vibration occurring from unbalanced moment in the 2nd order of the main engine.

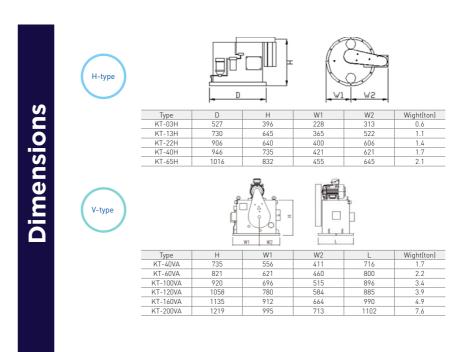
Required size of vibromotive force is determined according to the horizontal distance between the main engine center and vibromotive compensation device, MCR, and M2v.

**Trial operation time** can be greatly **reduced** using optimal control phase and control following algorithm. **High energy saving effect** is created by the function to select and control the speed of ship as required for vibration reduction.



### Major components of the system

- Vibration compensator (electric balancer): device that generates vibro-motive force
- Control panel: system management and control
- Encoder unit: acquisition of speed and phase of the main engine



# 

Diagram

**Compensator Selection** 

# Major functions of the system

- Reduced trial
  operation time and
  cost using a function
  that automatically
  computes optimal
  control phase and
  necessary vibromotive force
- Large energy reduction effect using a function to stop operation in M/E speed section where vibration damping is unnecessary and to start operation in necessary sections
- Control can be adjusted without external devices such as hydraulic system.
- Control performance
   was improved by
   removal of phase
   deviation when
   acquiring phase
   using encoder.



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