

Vibration Compensator EMC Series (Electric Moment Compensator)







Vertical Type

- Effectively decreases vibrations that are difficult to manage through manual methods.
- Cost-effective and quick solution for reducing ship propulsion







Horizontal Type

Horizontal compensation device is installed on the deck house or engine top to reduce vibro-motive force caused by H or X-moment of the main engine guideforce, decreasing vibrations in the ship girder, D/H and main engine body.

Vertical Type

Vertical compensation device is installed in the steering gear room or on the mooring desk and used to effective reduce the vertical hull girder vibration occurring from unbalanced moment in the 2nd order of the main engine.

Required size of vibromotive force is determined according to the horizontal distance between the main engine center and vibromotive compensation device, MCR, and M2v.

Trial operation time can be greatly **reduced** using optimal control phase and control following algorithm. **High energy saving effect** is created by the function to select and control the speed of ship as required for vibration reduction.



Dimensions

Compensator Selection Diagram

Major components of the system

- Vibration compensator (electric balancer): device that generates vibro-motive force
- Control panel: system management and control
- Encoder unit: acquisition of speed and phase of the main engine

H-type Type KT-03H KT-13H Wight(ton) 527 730 906 228 365 KT-22H 640 735 400 606 V-type H 735 821 Wight(ton) KT-60VA 800 621 460 KT-100VA KT-120VA 920 1058 515 584 896 885 ΚΤ-16ΠVΔ

Major functions of the system

- Reduced trial
 operation time and
 cost using a function
 that automatically
 computes optimal
 control phase and
 necessary vibro motive force
- reduction effect
 using a function to
 stop operation in M/E
 speed section where
 vibration damping
 is unnecessary and
 to start operation in
 necessary sections
- Control can be adjusted without external devices such as hydraulic system.
- Control performance was improved by removal of phase deviation when acquiring phase using encoder.



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15-17 Akti Kountouriotou, 185 34, Piraeus, Attica, Greece

> +30 210 4110 007 info@edit.com.gr www.edit.com.gr